



**Bilkent University**

Department of Economics

---

# Introduction to Vector Autoregression for Monetary Economics Research

---

Mahmut S. İpek

February 18, 2026

# What are we doing?

- ▶ Main objective:
  - ▶ Measure effects of monetary policy on the economy: magnitude, timing, and persistence.



# What are we doing?

- ▶ Main objective:
  - ▶ Measure effects of monetary policy on the economy: magnitude, timing, and persistence.
- ▶ Key challenge:
  - ▶ Endogeneity problem - simultaneous causality between variables.

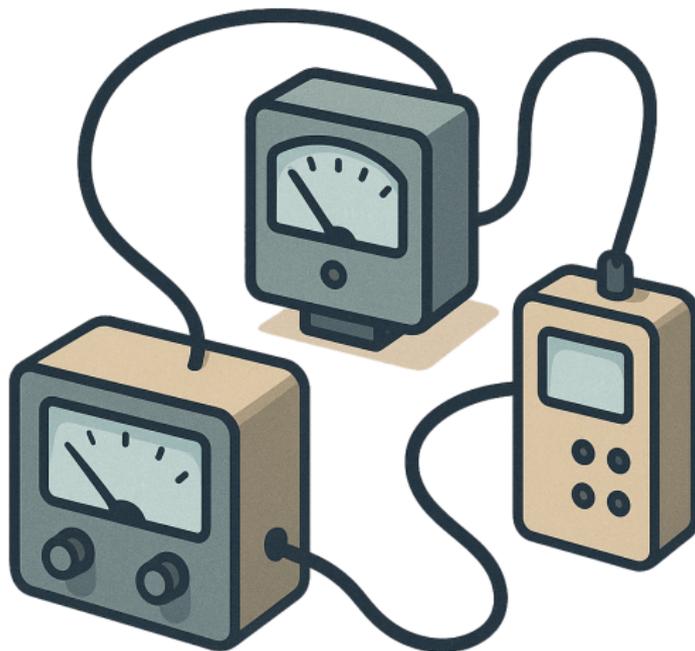


# What are we doing?

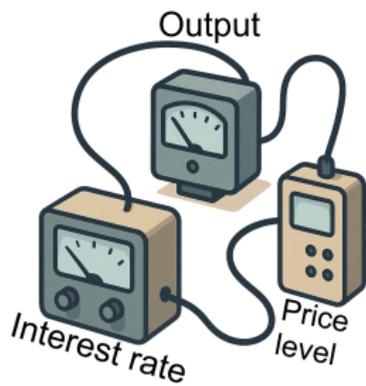
- ▶ Main objective:
  - ▶ Measure effects of monetary policy on the economy: magnitude, timing, and persistence.
- ▶ Key challenge:
  - ▶ Endogeneity problem - simultaneous causality between variables.
- ▶ A solution: **Vector Autoregression** approach.



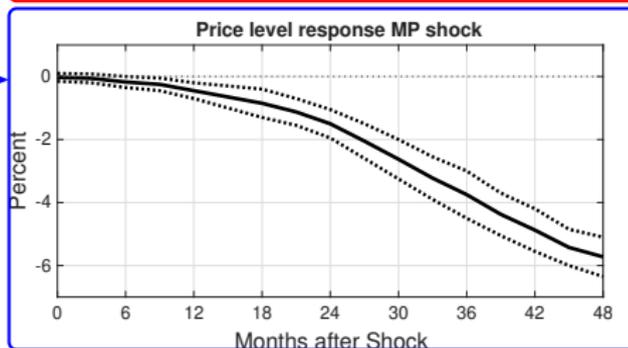
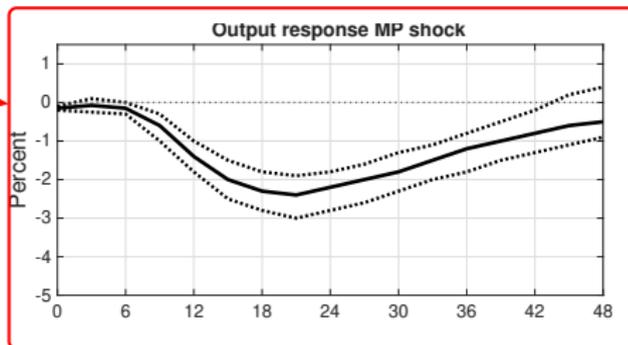
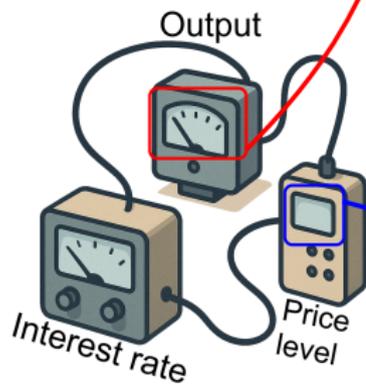
# What are we doing?



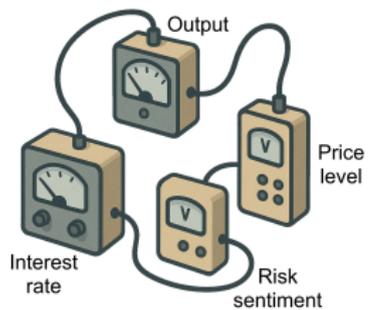
# A model



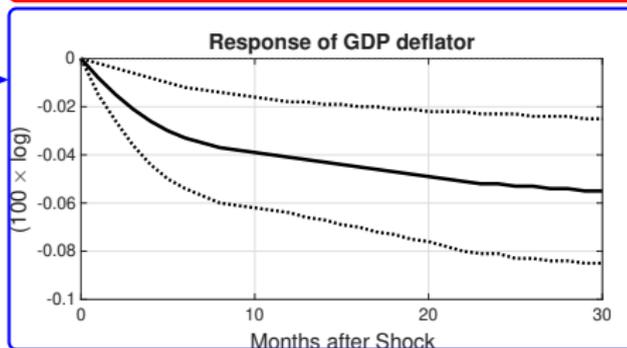
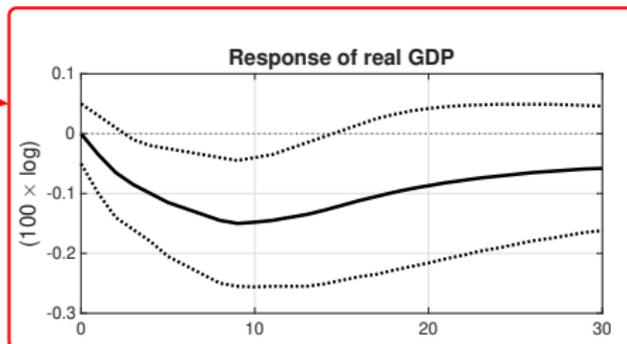
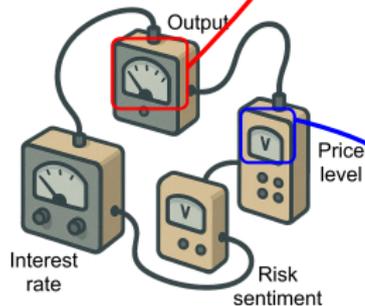
# A model



# Another model



# Another model



# What is autoregression anyway?

## regress (n.)

late 14c., *regresse*, “a return, passage back, act of going back,” from Latin *regressus* “a return, retreat, a going back,” noun use of past participle of *regredi* “to go back,” from *re-* “back” (see *re-*) + *gradi* “to step, walk” (from PIE root *\*ghredh-* “to walk, go”).

More common in legal language. Mental sense of “act of working back from an effect to a cause” is from 1610s.

also from late 14c.

Source: [etymonline.com](http://etymonline.com)



# What is autoregression anyway?

## regress (n.)

late 14c., *regresse*, “a return, passage back, act of going back,” from Latin *regressus* “a return, retreat, a going back,” noun use of past participle of *regredi* “to go back,” from *re-* “back” (see *re-*) + *gradi* “to step, walk” (from PIE root *\*ghredh-* “to walk, go”).

More common in legal language. Mental sense of “act of working back from an effect to a cause” is from 1610s.

also from late 14c.

Source: [etymonline.com](http://etymonline.com)

Usual regression:  $y_t = \beta X_t + e_t$



# What is autoregression anyway?

## regress (n.)

late 14c., *regresse*, “a return, passage back, act of going back,” from Latin *regressus* “a return, retreat, a going back,” noun use of past participle of *regredi* “to go back,” from *re-* “back” (see *re-*) + *gradi* “to step, walk” (from PIE root *\*ghredh-* “to walk, go”).

More common in legal language. Mental sense of “act of working back from an effect to a cause” is from 1610s.

also from late 14c.

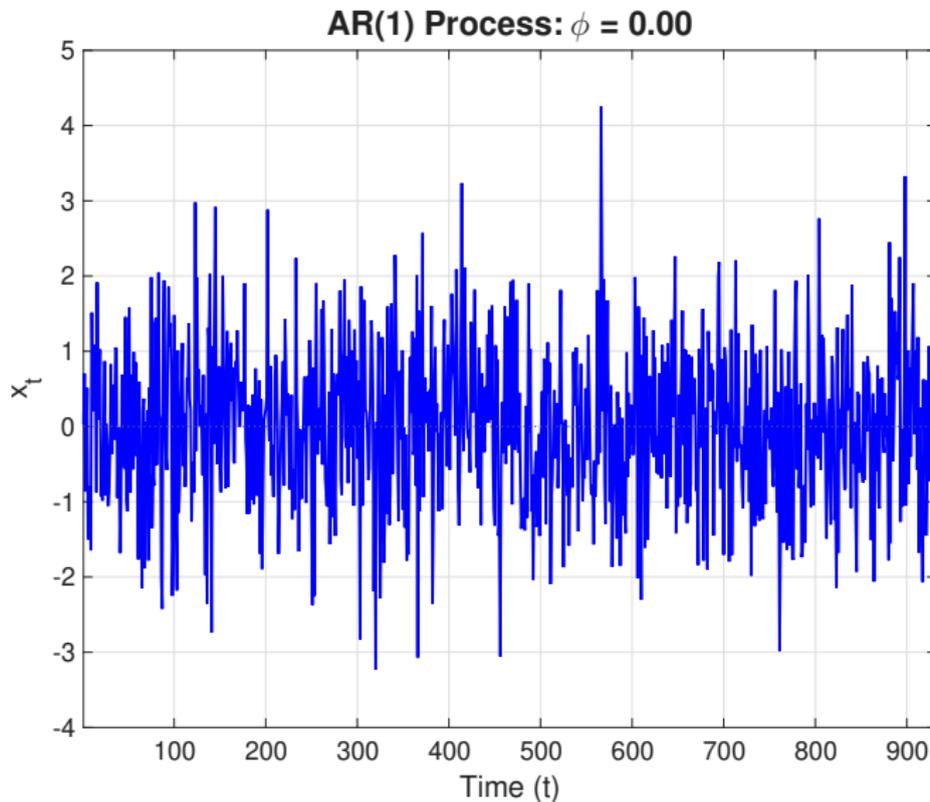
Source: [etymonline.com](http://etymonline.com)

Usual regression:  $y_t = \beta X_t + e_t$

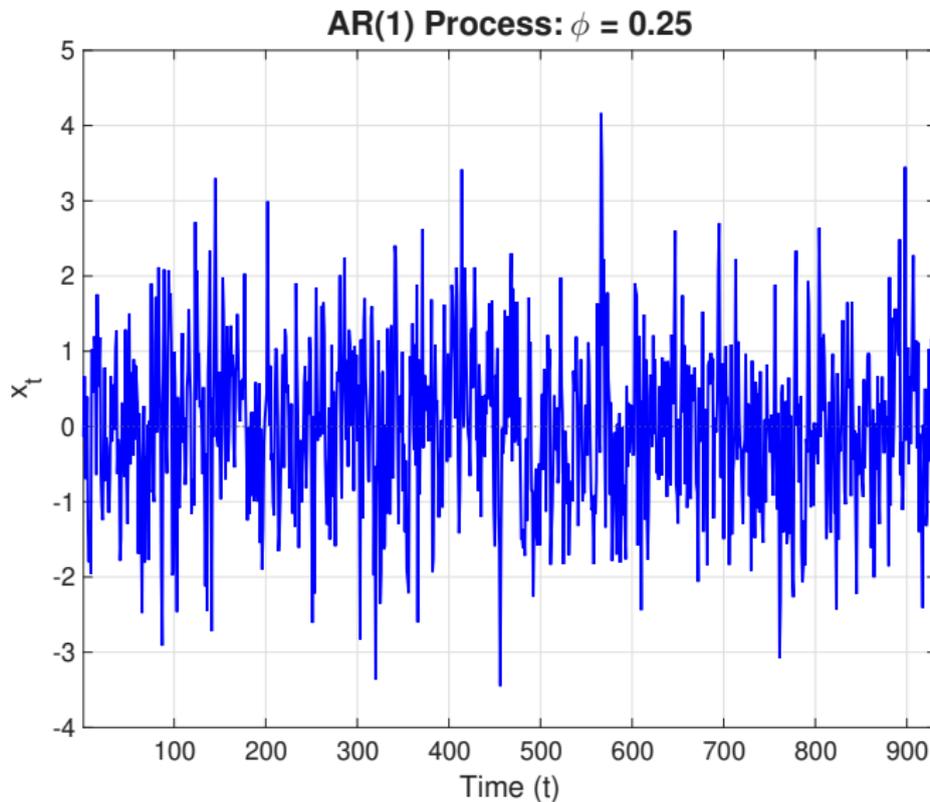
Autoregression:  $X_t = \phi X_{t-1} + w_t$



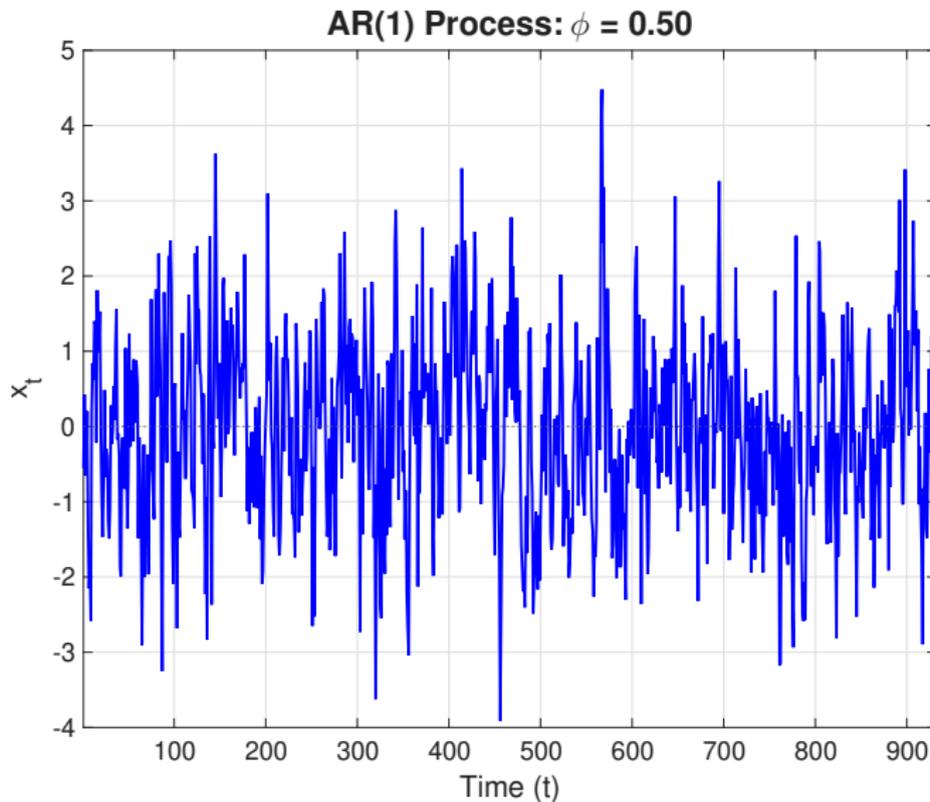
# AR(1) process



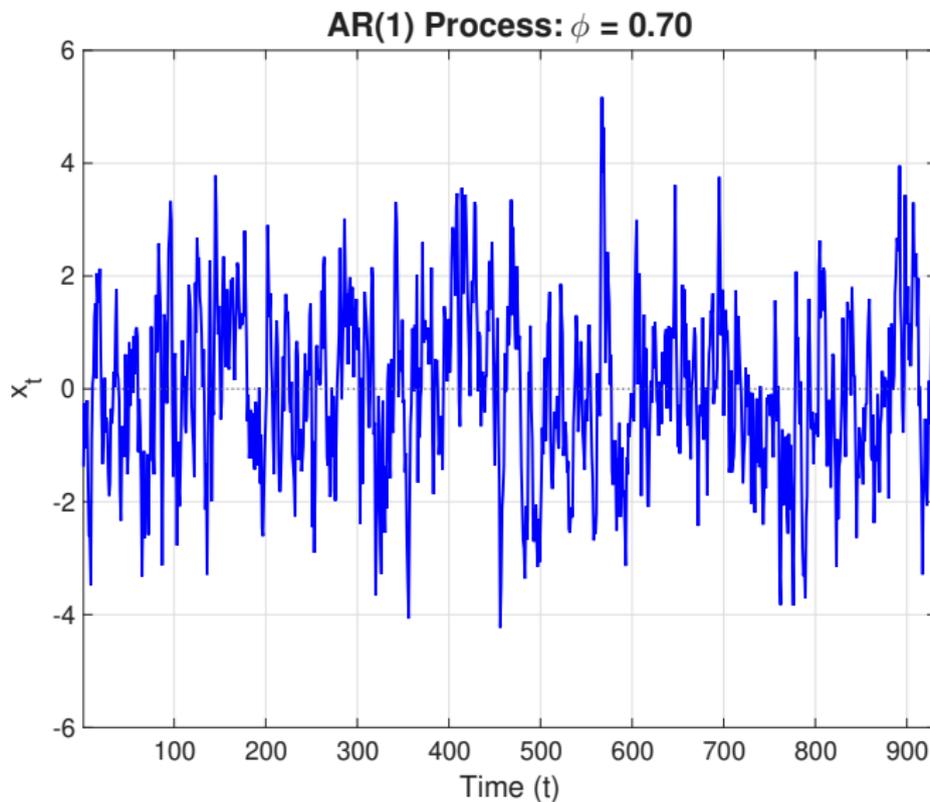
# AR(1) process



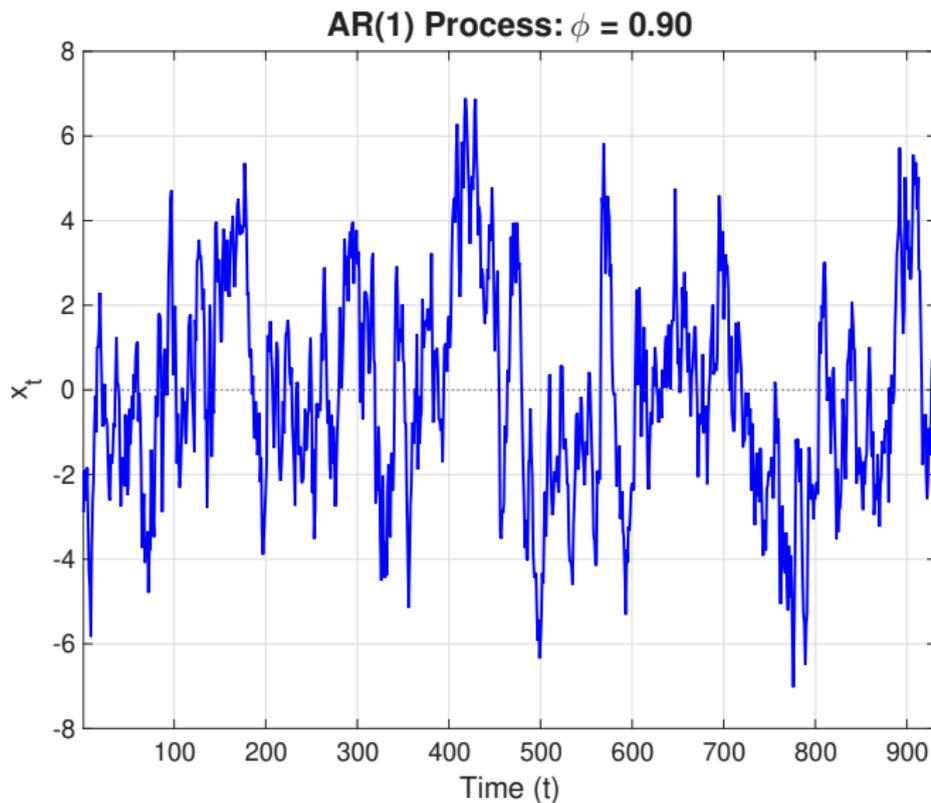
# AR(1) process



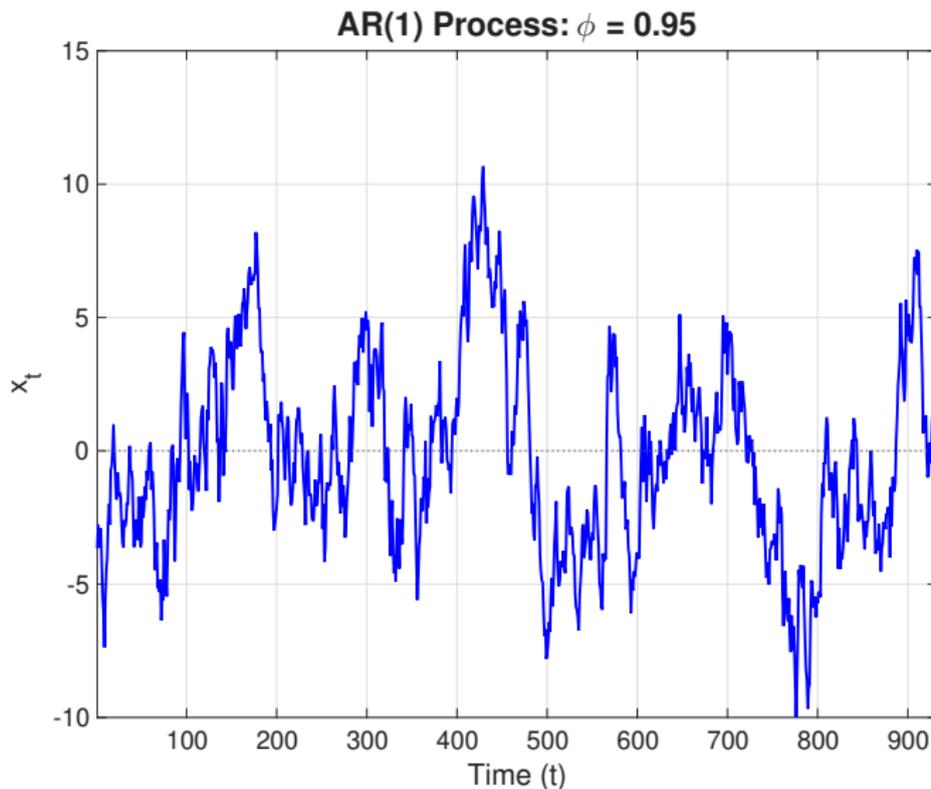
# AR(1) process



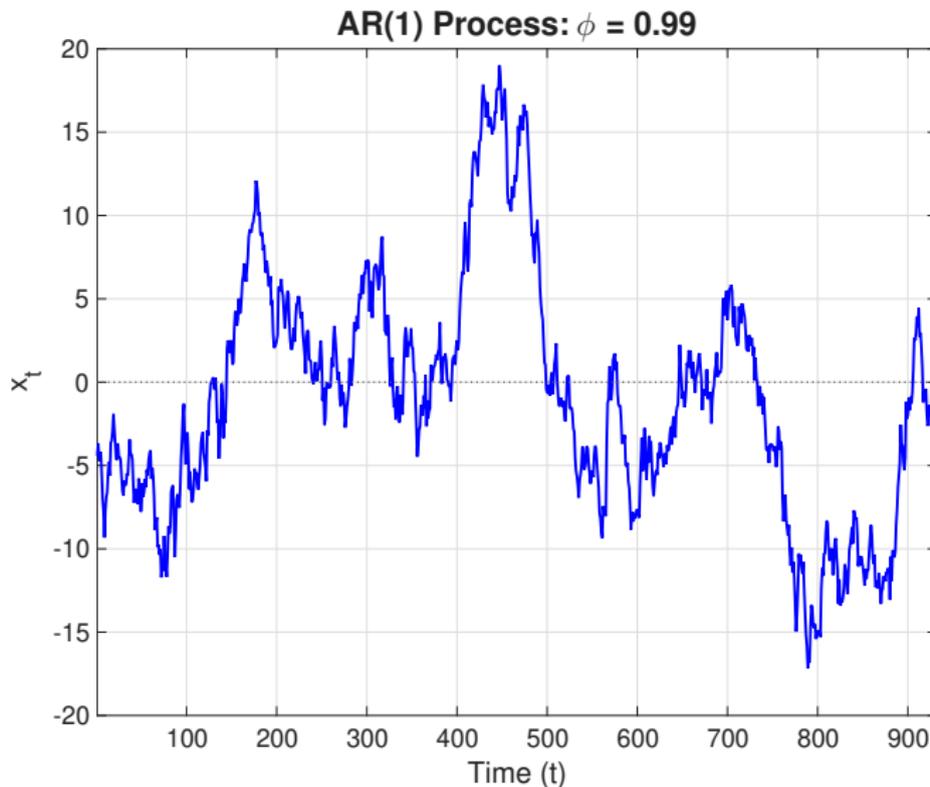
# AR(1) process



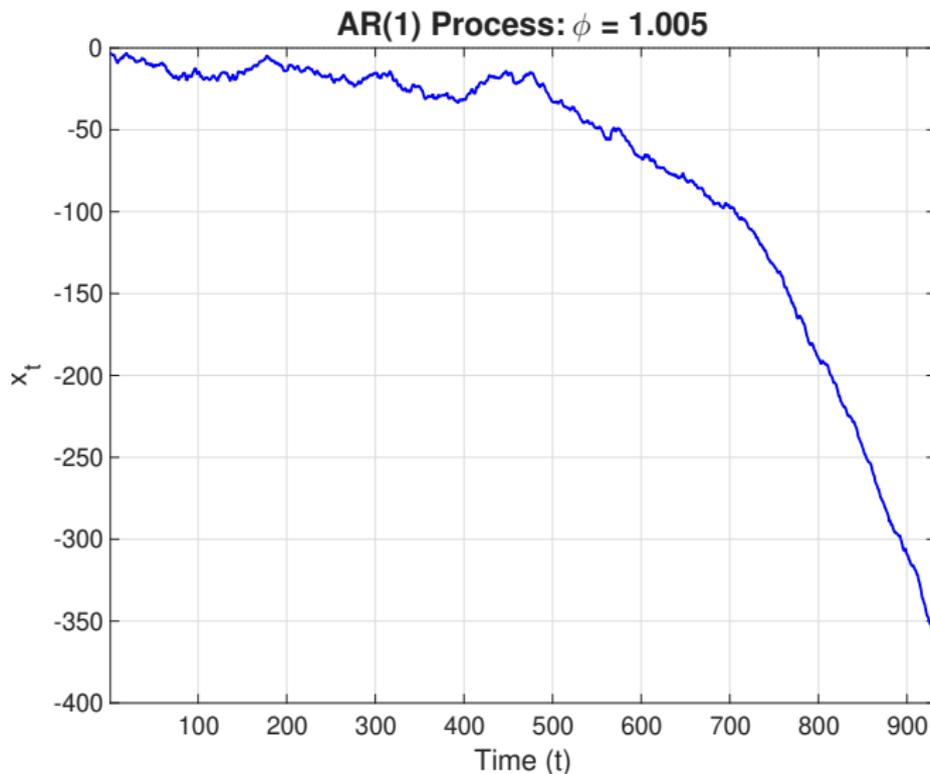
# AR(1) process



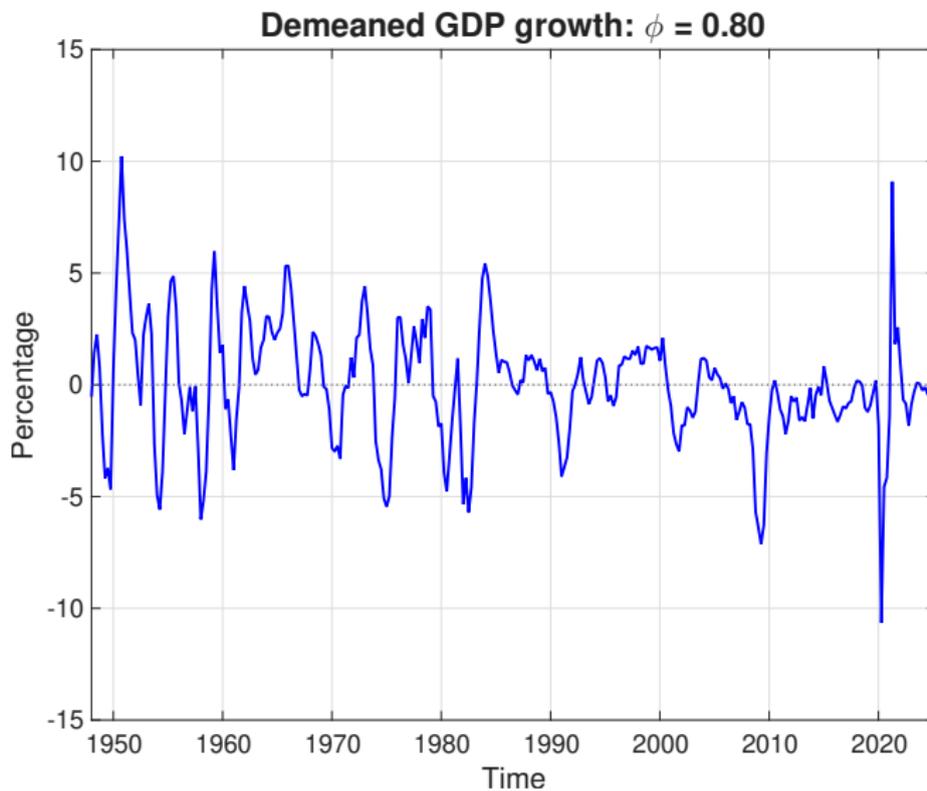
# AR(1) process



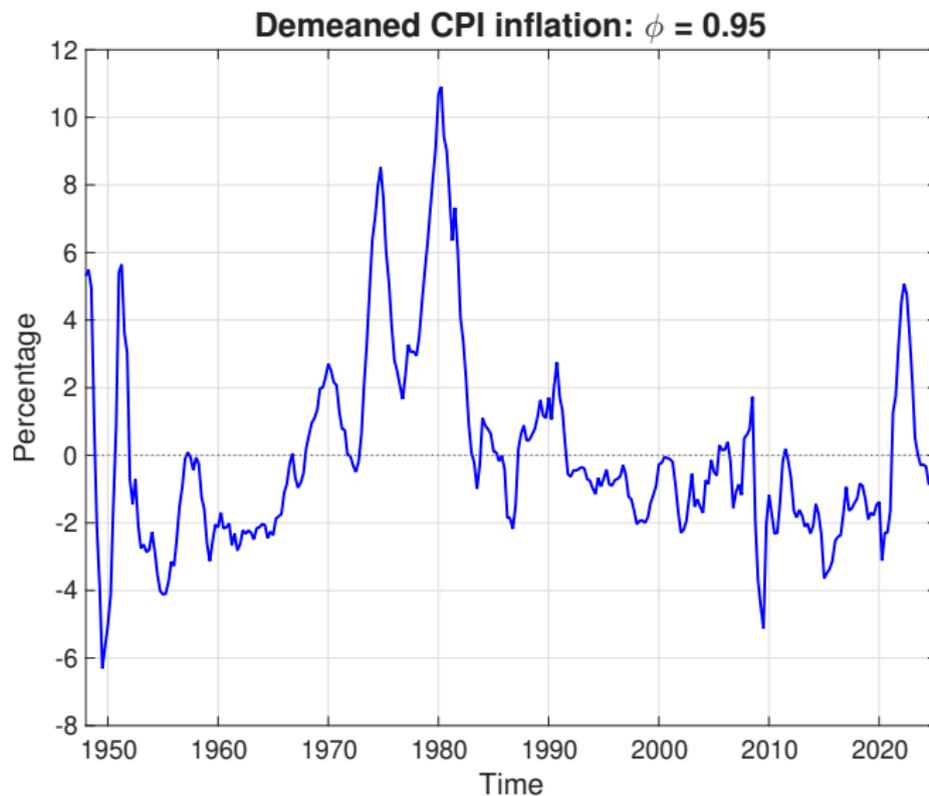
# AR(1) process



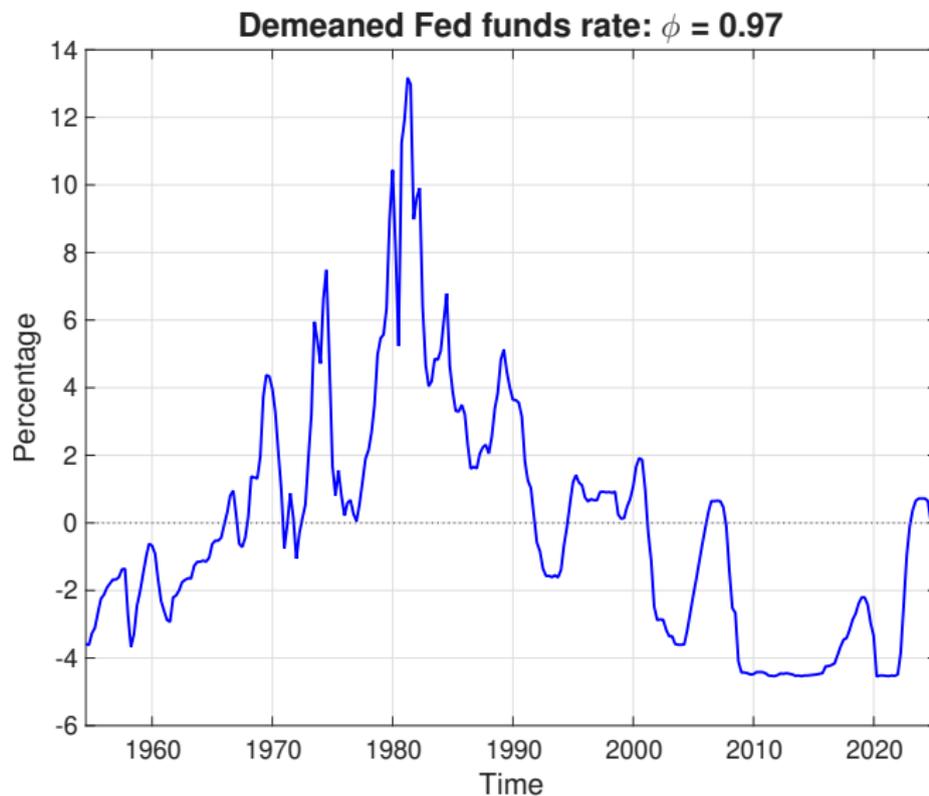
# Real data example



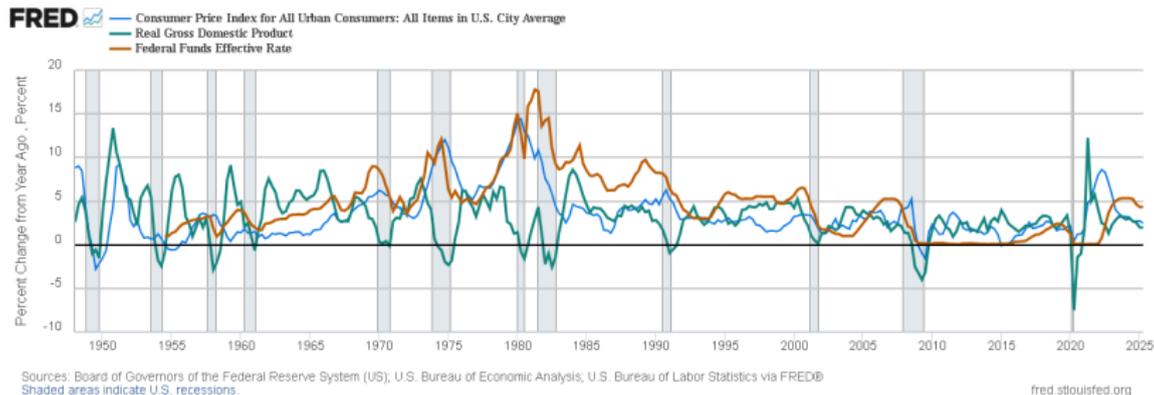
# Real data example



# Real data example



# Interdependent economic variables



So, we can model these variables as autoregressive processes.

# Interdependent economic variables

$$Y_t = \phi_Y Y_{t-1} + u_{1,t} \quad (\text{ignores } \pi_t, i_t)$$

$$\pi_t = \phi_\pi \pi_{t-1} + u_{2,t} \quad (\text{ignores } Y_t, i_t)$$

$$i_t = \phi_i i_{t-1} + u_{3,t} \quad (\text{ignores } Y_t, \pi_t)$$

$Y_t$  should be  $\Delta \log Y_t$  but I dropped  $\Delta \log$  for brevity.



$$Y_t = \phi_{11} Y_{t-1} + \phi_{12} \pi_{t-1} + \phi_{13} i_{t-1} + u_{1,t}$$

$$\pi_t = \phi_{21} Y_{t-1} + \phi_{22} \pi_{t-1} + \phi_{23} i_{t-1} + u_{2,t}$$

$$i_t = \phi_{31} Y_{t-1} + \phi_{32} \pi_{t-1} + \phi_{33} i_{t-1} + u_{3,t}$$

$$x_t = \begin{bmatrix} Y_t \\ \pi_t \\ i_t \end{bmatrix} = \begin{bmatrix} \phi_{11} & \phi_{12} & \phi_{13} \\ \phi_{21} & \phi_{22} & \phi_{23} \\ \phi_{31} & \phi_{32} & \phi_{33} \end{bmatrix} \begin{bmatrix} Y_{t-1} \\ \pi_{t-1} \\ i_{t-1} \end{bmatrix} + \begin{bmatrix} u_{1,t} \\ u_{2,t} \\ u_{3,t} \end{bmatrix}$$

$$x_t = Ax_{t-1} + u_t$$

$$x_t = \begin{bmatrix} Y_t \\ \pi_t \\ i_t \end{bmatrix} = \begin{bmatrix} \phi_{11} & \phi_{12} & \phi_{13} \\ \phi_{21} & \phi_{22} & \phi_{23} \\ \phi_{31} & \phi_{32} & \phi_{33} \end{bmatrix} \begin{bmatrix} Y_{t-1} \\ \pi_{t-1} \\ i_{t-1} \end{bmatrix} + \begin{bmatrix} u_{1,t} \\ u_{2,t} \\ u_{3,t} \end{bmatrix}$$

$$x_t = Ax_{t-1} + u_t$$

$Y_0, \pi_0, i_0$  are the long run steady state levels, normalized to zero.

# VAR ignoring ...

$$x_1 = Ax_0 + u_1$$
$$\underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{x_1} = \underbrace{\begin{bmatrix} \phi_{11} & \phi_{12} & \phi_{13} \\ \phi_{21} & \phi_{22} & \phi_{23} \\ \phi_{31} & \phi_{32} & \phi_{33} \end{bmatrix}}_A \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{x_0} + \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{u_1}$$

# VAR ignoring ...

$$x_1 = Ax_0 + u_1$$

$$\underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{x_1} = \underbrace{\begin{bmatrix} \phi_{11} & \phi_{12} & \phi_{13} \\ \phi_{21} & \phi_{22} & \phi_{23} \\ \phi_{31} & \phi_{32} & \phi_{33} \end{bmatrix}}_A \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{x_0} + \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{u_1}$$

$$x_2 = Ax_1$$

$$\underbrace{\begin{bmatrix} \phi_{13} \\ \phi_{23} \\ \phi_{33} \end{bmatrix}}_{x_2} = \underbrace{\begin{bmatrix} \phi_{11} & \phi_{12} & \phi_{13} \\ \phi_{21} & \phi_{22} & \phi_{23} \\ \phi_{31} & \phi_{32} & \phi_{33} \end{bmatrix}}_A \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{x_1}$$

# VAR ignoring ...

$$x_1 = Ax_0 + u_1 \quad \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{x_1} = \underbrace{\begin{bmatrix} \phi_{11} & \phi_{12} & \phi_{13} \\ \phi_{21} & \phi_{22} & \phi_{23} \\ \phi_{31} & \phi_{32} & \phi_{33} \end{bmatrix}}_A \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{x_0} + \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{u_1}$$

$$x_2 = Ax_1 \quad \underbrace{\begin{bmatrix} \phi_{13} \\ \phi_{23} \\ \phi_{33} \end{bmatrix}}_{x_2} = \underbrace{\begin{bmatrix} \phi_{11} & \phi_{12} & \phi_{13} \\ \phi_{21} & \phi_{22} & \phi_{23} \\ \phi_{31} & \phi_{32} & \phi_{33} \end{bmatrix}}_A \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{x_1}$$

...

$$x_t = A^{t-1}x_1 \quad \underbrace{\begin{bmatrix} Y_t \\ \pi_t \\ i_t \end{bmatrix}}_{x_t} = A \underbrace{\begin{bmatrix} Y_t \\ \pi_t \\ i_t \end{bmatrix}}_{x_{t-1}}$$



# VAR ignoring contemporaneous interactions

$$Y_t = \phi_{11} Y_{t-1} + \phi_{12} \pi_{t-1} + \phi_{13} i_{t-1} + u_{1,t}$$

$$\pi_t = \phi_{21} Y_{t-1} + \phi_{22} \pi_{t-1} + \phi_{23} i_{t-1} + u_{2,t}$$

$$i_t = \phi_{31} Y_{t-1} + \phi_{32} \pi_{t-1} + \phi_{33} i_{t-1} + u_{3,t}$$



# VAR with contemporaneous interactions

Note: Minuses are only for easier exposition.

$$Y_t = -b_{12}\pi_t - b_{13}i_t + \phi_{11}Y_{t-1} + \phi_{12}\pi_{t-1} + \phi_{13}i_{t-1} + \varepsilon_{Y,t}$$

$$\pi_t = -b_{21}Y_t - b_{23}i_t + \phi_{21}Y_{t-1} + \phi_{22}\pi_{t-1} + \phi_{23}i_{t-1} + \varepsilon_{\pi,t}$$

$$i_t = -b_{31}Y_t - b_{32}\pi_t + \phi_{31}Y_{t-1} + \phi_{32}\pi_{t-1} + \phi_{33}i_{t-1} + \varepsilon_{i,t}$$



# VAR with contemporaneous interactions

Note: Minuses are only for easier exposition.

$$Y_t = -b_{12}\pi_t - b_{13}i_t + \phi_{11}Y_{t-1} + \phi_{12}\pi_{t-1} + \phi_{13}i_{t-1} + \varepsilon_{Y,t}$$

$$\pi_t = -b_{21}Y_t - b_{23}i_t + \phi_{21}Y_{t-1} + \phi_{22}\pi_{t-1} + \phi_{23}i_{t-1} + \varepsilon_{\pi,t}$$

$$i_t = -b_{31}Y_t - b_{32}\pi_t + \phi_{31}Y_{t-1} + \phi_{32}\pi_{t-1} + \phi_{33}i_{t-1} + \varepsilon_{i,t}$$

$$Y_t = \tilde{\phi}_{11}Y_{t-1} + \tilde{\phi}_{12}\pi_{t-1} + \tilde{\phi}_{13}i_{t-1} + \underbrace{-b_{12}\varepsilon_{\pi,t} - b_{13}\varepsilon_{i,t} + \varepsilon_{Y,t}}_{u_{1,t}}$$

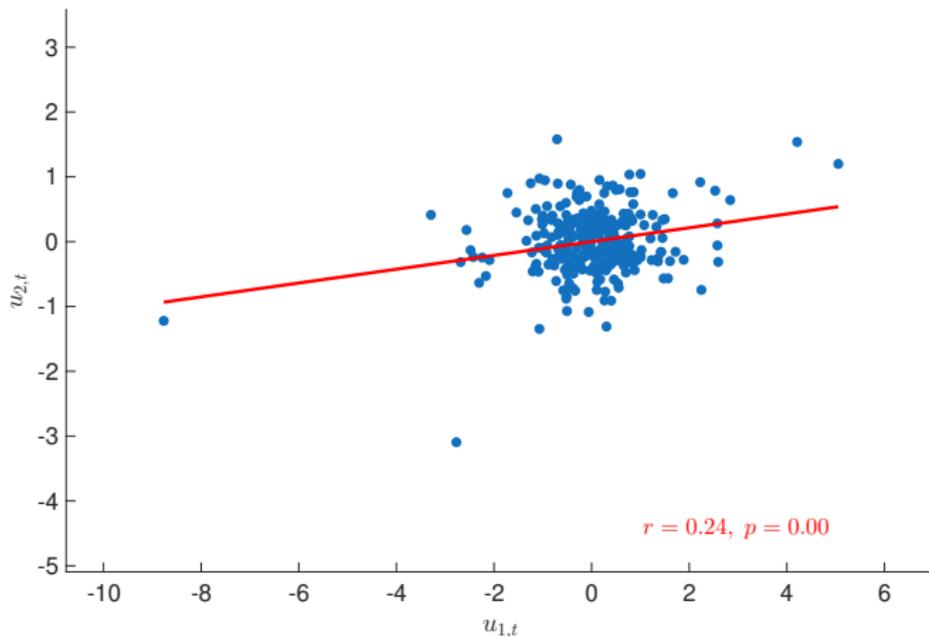
$$i_t = \tilde{\phi}_{31}Y_{t-1} + \tilde{\phi}_{32}\pi_{t-1} + \tilde{\phi}_{33}i_{t-1} + \underbrace{-b_{31}\varepsilon_{Y,t} - b_{32}\varepsilon_{\pi,t} + \varepsilon_{i,t}}_{u_{2,t}}$$

$$\pi_t = \tilde{\phi}_{12}Y_{t-1} + \tilde{\phi}_{22}\pi_{t-1} + \tilde{\phi}_{23}i_{t-1} + \underbrace{-b_{21}\varepsilon_{Y,t} - b_{23}\varepsilon_{i,t} + \varepsilon_{\pi,t}}_{u_{3,t}}$$

These residuals are correlated with each other.



# Correlation between GDP and inflation residuals



# VAR with contemporaneous interactions

$$\begin{aligned}Y_t &= -b_{12}\pi_t - b_{13}i_t + \phi_{11}Y_{t-1} + \phi_{12}\pi_{t-1} + \phi_{13}i_{t-1} + \varepsilon_{Y,t} \\ \pi_t &= -b_{21}Y_t - b_{23}i_t + \phi_{21}Y_{t-1} + \phi_{22}\pi_{t-1} + \phi_{23}i_{t-1} + \varepsilon_{\pi,t} \\ i_t &= -b_{31}Y_t - b_{32}\pi_t + \phi_{31}Y_{t-1} + \phi_{32}\pi_{t-1} + \phi_{33}i_{t-1} + \varepsilon_{i,t}\end{aligned}$$



# VAR with contemporaneous interactions

$$\begin{aligned}Y_t &= -b_{12}\pi_t - b_{13}i_t + \phi_{11}Y_{t-1} + \phi_{12}\pi_{t-1} + \phi_{13}i_{t-1} + \varepsilon_{Y,t} \\ \pi_t &= -b_{21}Y_t - b_{23}i_t + \phi_{21}Y_{t-1} + \phi_{22}\pi_{t-1} + \phi_{23}i_{t-1} + \varepsilon_{\pi,t} \\ i_t &= -b_{31}Y_t - b_{32}\pi_t + \phi_{31}Y_{t-1} + \phi_{32}\pi_{t-1} + \phi_{33}i_{t-1} + \varepsilon_{i,t}\end{aligned}$$

$$\begin{aligned}Y_t + b_{12}\pi_t + b_{13}i_t &= \phi_{11}Y_{t-1} + \phi_{12}\pi_{t-1} + \phi_{13}i_{t-1} + \varepsilon_{Y,t} \\ b_{21}Y_t + \pi_t + b_{23}i_t &= \phi_{21}Y_{t-1} + \phi_{22}\pi_{t-1} + \phi_{23}i_{t-1} + \varepsilon_{\pi,t} \\ b_{31}Y_t + b_{32}\pi_t + i_t &= \phi_{31}Y_{t-1} + \phi_{32}\pi_{t-1} + \phi_{33}i_{t-1} + \varepsilon_{i,t}\end{aligned}$$



# Structural Vector Autoregression (SVAR)

$$\underbrace{\begin{bmatrix} 1 & b_{12} & b_{13} \\ b_{21} & 1 & b_{23} \\ b_{31} & b_{32} & 1 \end{bmatrix}}_{B_0} \underbrace{\begin{bmatrix} Y_t \\ \pi_t \\ i_t \end{bmatrix}}_{x_t} = B_1 \underbrace{\begin{bmatrix} Y_{t-1} \\ \pi_{t-1} \\ i_{t-1} \end{bmatrix}}_{x_{t-1}} + \underbrace{\begin{bmatrix} \varepsilon_{Y,t} \\ \varepsilon_{\pi,t} \\ \varepsilon_{i,t} \end{bmatrix}}_{\varepsilon_t}$$

# Structural Vector Autoregression (SVAR)

$$\underbrace{\begin{bmatrix} 1 & b_{12} & b_{13} \\ b_{21} & 1 & b_{23} \\ b_{31} & b_{32} & 1 \end{bmatrix}}_{B_0} \underbrace{\begin{bmatrix} Y_t \\ \pi_t \\ i_t \end{bmatrix}}_{x_t} = B_1 \underbrace{\begin{bmatrix} Y_{t-1} \\ \pi_{t-1} \\ i_{t-1} \end{bmatrix}}_{x_{t-1}} + \underbrace{\begin{bmatrix} \varepsilon_{Y,t} \\ \varepsilon_{\pi,t} \\ \varepsilon_{i,t} \end{bmatrix}}_{\varepsilon_t}$$
$$B_0 x_t = B_1 x_{t-1} + \varepsilon_t$$

**Key insight:**  $B_0$  captures contemporaneous relationships between variables

# From SVAR to reduced form VAR

$$B_0 y_t = B_1 y_{t-1} + \varepsilon_t$$

$$y_t = \underbrace{A_1}_{B_0^{-1} B_1} y_{t-1} + B_0^{-1} \varepsilon_t$$



# From SVAR to reduced form VAR

$$B_0 y_t = B_1 y_{t-1} + \varepsilon_t$$

$$y_t = \underbrace{A_1}_{B_0^{-1} B_1} y_{t-1} + B_0^{-1} \varepsilon_t$$

$$\underbrace{\begin{bmatrix} Y_t \\ \pi_t \\ i_t \end{bmatrix}}_{y_t} = A_1 \underbrace{\begin{bmatrix} Y_{t-1} \\ \pi_{t-1} \\ i_{t-1} \end{bmatrix}}_{y_{t-1}} + B_0^{-1} \underbrace{\begin{bmatrix} \varepsilon_{Y,t} \\ \varepsilon_{\pi,t} \\ \varepsilon_{i,t} \end{bmatrix}}_{\varepsilon_t}$$

**Key transformation:** Reduced form can be estimated, but the impact matrix requires identification to obtain the propagation mechanism.



# Impulse response function: Methodological setup

$$\underbrace{\begin{bmatrix} Y_t \\ \pi_t \\ i_t \end{bmatrix}}_{x_t} = A_1 \underbrace{\begin{bmatrix} Y_{t-1} \\ \pi_{t-1} \\ i_{t-1} \end{bmatrix}}_{x_{t-1}} + \underbrace{\begin{bmatrix} \tilde{b}_{11} & \tilde{b}_{12} & \tilde{b}_{13} \\ \tilde{b}_{21} & \tilde{b}_{22} & \tilde{b}_{23} \\ \tilde{b}_{31} & \tilde{b}_{32} & \tilde{b}_{33} \end{bmatrix}}_{B_0^{-1}} \underbrace{\begin{bmatrix} \varepsilon_{Y,t} \\ \varepsilon_{\pi,t} \\ \varepsilon_{i,t} \end{bmatrix}}_{\varepsilon_t}$$

**Goal:** Trace the effects of a one-unit shock to the monetary policy equation (interest rate shock)

# Impulse response analysis: Period 0 (Baseline equilibrium)

$$\underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{y_0} = A_1 \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{y_{-1}} + B_0^{-1} \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\varepsilon_0}$$

**Initial state:** All variables at long-run equilibrium (normalized to zero)

# Impulse response analysis: Period 1 (Initial shock impact)

$$\underbrace{\begin{bmatrix} Y_1 \\ \pi_1 \\ i_1 \end{bmatrix}}_{y_1} = A_1 \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{y_0} + \underbrace{\begin{bmatrix} \tilde{b}_{11} & \tilde{b}_{12} & \tilde{b}_{13} \\ \tilde{b}_{21} & \tilde{b}_{22} & \tilde{b}_{23} \\ \tilde{b}_{31} & \tilde{b}_{32} & \tilde{b}_{33} \end{bmatrix}}_{B_0^{-1}} \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{\varepsilon_1}$$

**Impact period:** One-unit structural shock to interest rate equation

# Impulse response analysis: Period 2 (First-order propagation)

$$\underbrace{\begin{bmatrix} Y_2 \\ \pi_2 \\ i_2 \end{bmatrix}}_{y_2} = A_1 \underbrace{\begin{bmatrix} Y_1 \\ \pi_1 \\ i_1 \end{bmatrix}}_{y_1} + B_0^{-1} \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\varepsilon_2}$$

## Impulse response analysis: Period 2 (First-order propagation)

$$\underbrace{\begin{bmatrix} Y_2 \\ \pi_2 \\ i_2 \end{bmatrix}}_{y_2} = A_1 \underbrace{\begin{bmatrix} Y_1 \\ \pi_1 \\ i_1 \end{bmatrix}}_{y_1} + B_0^{-1} \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_{\varepsilon_2}$$
$$y_2 = A_1 \left[ B_0^{-1} \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{\varepsilon_1} \right]$$

**First propagation:** Effects transmitted through lagged relationships

# Impulse response analysis: Period 3 (Second-order propagation)

$$y_3 = A_1^2 \left[ B_0^{-1} \underbrace{\begin{bmatrix} 0 \\ 0 \\ \mathbf{1} \end{bmatrix}}_{\varepsilon_1} \right]$$

**Second propagation:** Compounding effects through dynamic interactions

# General impulse response function

$$IRF_t^{(MP)} = A_1^{t-1} B_0^{-1} \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{\text{MP shock}}$$

# General impulse response function

$$IRF_t^{(MP)} = A_1^{t-1} B_0^{-1} \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{\text{MP shock}}$$

## Key properties:

- ▶ IRF depends on autoregressive coefficients ( $A_1$ ) and impact matrix ( $B_0^{-1}$ )
- ▶ Contemporaneous effects captured by  $B_0^{-1}$
- ▶ Can trace response of any variable to any structural shock

$p > 1$  lags?

$$\text{Impulse: } R_0 = B_0^{-1} \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{\text{MP shock}}$$

$$\text{Response at } (t = 1): R_1 = A_1 R_0$$

$$\text{Response at } (t = 2): R_2 = A_1 R_1 + A_2 R_0$$

$$\text{Response at } (t = 3): R_3 = A_1 R_2 + A_2 R_1 + A_3 R_0$$

$\vdots$

$$\text{Response at } (t = h > 0): R_h = \sum_{i=1}^{\min\{h,p\}} A_i R_{h-i}$$



# The identification problem

**Key challenge:** We can estimate the reduced form VAR, but how do we recover the structural parameters in  $B_0^{-1}$ ?



# The identification problem

**Key challenge:** We can estimate the reduced form VAR, but how do we recover the structural parameters in  $B_0^{-1}$ ?

$$\text{Reduced form: } y_t = A_1 y_{t-1} + \underbrace{B_0^{-1} \varepsilon_t}_{u_t}$$



# The identification problem

**Key challenge:** We can estimate the reduced form VAR, but how do we recover the structural parameters in  $B_0^{-1}$ ?

$$\text{Reduced form: } y_t = A_1 y_{t-1} + \underbrace{B_0^{-1} \varepsilon_t}_{u_t}$$

## Problem:

- ▶ We observe  $u_t$  but not  $\varepsilon_t$
- ▶ Need to identify  $B_0^{-1}$  to compute impulse responses
- ▶ With 3 variables: 9 elements in  $B_0^{-1}$ , but only 6 unique elements in  $\text{Cov}(u_t)$  (Elaborated in the next slide)



# Identification with 3 variables

Let

$$B_0^{-1} \equiv \tilde{B} = \begin{bmatrix} \tilde{b}_{11} & \tilde{b}_{12} & \tilde{b}_{13} \\ \tilde{b}_{21} & \tilde{b}_{22} & \tilde{b}_{23} \\ \tilde{b}_{31} & \tilde{b}_{32} & \tilde{b}_{33} \end{bmatrix}, \quad \varepsilon_t \sim \mathcal{N}(0, I_3) \quad u_t = \tilde{B}\varepsilon_t$$



# Identification with 3 variables

Let

$$B_0^{-1} \equiv \tilde{B} = \begin{bmatrix} \tilde{b}_{11} & \tilde{b}_{12} & \tilde{b}_{13} \\ \tilde{b}_{21} & \tilde{b}_{22} & \tilde{b}_{23} \\ \tilde{b}_{31} & \tilde{b}_{32} & \tilde{b}_{33} \end{bmatrix}, \quad \varepsilon_t \sim \mathcal{N}(0, I_3) \quad u_t = \tilde{B}\varepsilon_t$$

Then

$$\Sigma_u \equiv \text{Cov}(u_t) = \tilde{B}\tilde{B}^\top = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{12} & \sigma_{22} & \sigma_{23} \\ \sigma_{13} & \sigma_{23} & \sigma_{33} \end{bmatrix}$$



# Identification with 3 variables

Let

$$B_0^{-1} \equiv \tilde{B} = \begin{bmatrix} \tilde{b}_{11} & \tilde{b}_{12} & \tilde{b}_{13} \\ \tilde{b}_{21} & \tilde{b}_{22} & \tilde{b}_{23} \\ \tilde{b}_{31} & \tilde{b}_{32} & \tilde{b}_{33} \end{bmatrix}, \quad \varepsilon_t \sim \mathcal{N}(0, I_3) \quad u_t = \tilde{B}\varepsilon_t$$

Then

$$\Sigma_u \equiv \text{Cov}(u_t) = \tilde{B}\tilde{B}^\top = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{12} & \sigma_{22} & \sigma_{23} \\ \sigma_{13} & \sigma_{23} & \sigma_{33} \end{bmatrix}$$

with entries (six unique equations):

$$\sigma_{11} = \tilde{b}_{11}^2 + \tilde{b}_{12}^2 + \tilde{b}_{13}^2$$

$$\sigma_{12} = \tilde{b}_{11}\tilde{b}_{21} + \tilde{b}_{12}\tilde{b}_{22} + \tilde{b}_{13}\tilde{b}_{23}$$

$$\sigma_{22} = \tilde{b}_{21}^2 + \tilde{b}_{22}^2 + \tilde{b}_{23}^2$$

$$\sigma_{13} = \tilde{b}_{11}\tilde{b}_{31} + \tilde{b}_{12}\tilde{b}_{32} + \tilde{b}_{13}\tilde{b}_{33}$$

$$\sigma_{33} = \tilde{b}_{31}^2 + \tilde{b}_{32}^2 + \tilde{b}_{33}^2$$

$$\sigma_{23} = \tilde{b}_{21}\tilde{b}_{31} + \tilde{b}_{22}\tilde{b}_{32} + \tilde{b}_{23}\tilde{b}_{33}$$

# Identification with 3 variables

- ▶ Unknowns: the 9 numbers  $\tilde{b}_{11}, \dots, \tilde{b}_{33}$ .
- ▶ Observables: the 6 numbers  $\sigma_{11}, \sigma_{22}, \sigma_{33}, \sigma_{12}, \sigma_{13}, \sigma_{23}$ .

Hence you need  $9 - 6 = 3$  additional restrictions (e.g. long-run restrictions, zero and sign restrictions) to pin down  $B_0^{-1}$  and thus the impulse responses.



## Theorem (Cholesky Factorization)

*Let  $A \in \mathbb{R}^{n \times n}$  be symmetric and positive definite with strictly positive diagonal entries. Then there exists a unique lower triangular matrix  $L \in \mathbb{R}^{n \times n}$  such that*

$$A = LL^T.$$

# Cholesky identification: Economic intuition

**Key idea:** Order variables by speed of response to shocks



# Cholesky identification: Economic intuition

**Key idea:** Order variables by speed of response to shocks  
Economic reasoning for monetary VAR:

- ▶ Output ( $Y$ ): Responds slowly due to adjustment costs
- ▶ Inflation ( $\pi$ ): Intermediate speed, some price stickiness
- ▶ Interest rate ( $i$ ): Responds immediately to all shocks

# Cholesky identification: Economic intuition

**Key idea:** Order variables by speed of response to shocks  
Economic reasoning for monetary VAR:

- ▶ Output ( $Y$ ): Responds slowly due to adjustment costs
- ▶ Inflation ( $\pi$ ): Intermediate speed, some price stickiness
- ▶ Interest rate ( $i$ ): Responds immediately to all shocks

**Ordering implication:**  $Y_t \rightarrow \pi_t \rightarrow i_t$

- ▶ Interest rate responds to output and inflation shocks *within the same period*
- ▶ Inflation responds to output shocks *within the same period*
- ▶ Output responds to other shocks only with a lag



**Restriction:** Make  $B_0$  lower triangular

$$B_0 = \begin{bmatrix} 1 & 0 & 0 \\ b_{21} & 1 & 0 \\ b_{31} & b_{32} & 1 \end{bmatrix}$$

**Restriction:** Make  $B_0$  lower triangular

$$B_0 = \begin{bmatrix} 1 & 0 & 0 \\ b_{21} & 1 & 0 \\ b_{31} & b_{32} & 1 \end{bmatrix}$$

**Structural system becomes:**

$$Y_t = \phi_{11} Y_{t-1} + \phi_{12} \pi_{t-1} + \phi_{13} i_{t-1} + \varepsilon_{Y,t}$$

$$\pi_t = b_{21} Y_t + \phi_{21} Y_{t-1} + \phi_{22} \pi_{t-1} + \phi_{23} i_{t-1} + \varepsilon_{\pi,t}$$

$$i_t = b_{31} Y_t + b_{32} \pi_t + \phi_{31} Y_{t-1} + \phi_{32} \pi_{t-1} + \phi_{33} i_{t-1} + \varepsilon_{i,t}$$

**Interpretation:** Output doesn't respond contemporaneously to other variables' shocks

# Cholesky decomposition implementation

**Step 1:** Estimate reduced form VAR to get  $\hat{\Sigma}_u = E[u_t u_t']$

**Step 2:** Perform Cholesky decomposition

$$\hat{\Sigma}_u = B_0^{-1} B_0^{-1\top}$$

where  $B_0^{-1}$  is lower triangular



# Cholesky decomposition implementation

**Step 1:** Estimate reduced form VAR to get  $\hat{\Sigma}_u = E[u_t u_t']$

**Step 2:** Perform Cholesky decomposition

$$\hat{\Sigma}_u = B_0^{-1} B_0^{-1\top}$$

where  $B_0^{-1}$  is lower triangular

**Step 3:** Identify structural shocks

$$B_0^{-1} \varepsilon_t = u_t$$



# Cholesky decomposition implementation

**Step 1:** Estimate reduced form VAR to get  $\hat{\Sigma}_u = E[u_t u_t']$

**Step 2:** Perform Cholesky decomposition

$$\hat{\Sigma}_u = B_0^{-1} B_0^{-1T}$$

where  $B_0^{-1}$  is lower triangular

**Step 3:** Identify structural shocks

$$B_0^{-1} \varepsilon_t = u_t$$

**Step 4:** Compute impulse responses

$$\text{IRF}_t^{(k)} = A_1^{t-1} B_0^{-1} e_k$$

where  $e_k$  is the  $k$ -th unit vector



# Cholesky example: Numerical illustration

Suppose we estimate the reduced form and obtain:

$$\hat{\Sigma}_u = \begin{bmatrix} 1.0 & 0.3 & 0.2 \\ 0.3 & 0.8 & 0.4 \\ 0.2 & 0.4 & 1.2 \end{bmatrix}$$



# Cholesky example: Numerical illustration

Suppose we estimate the reduced form and obtain:

$$\hat{\Sigma}_u = \begin{bmatrix} 1.0 & 0.3 & 0.2 \\ 0.3 & 0.8 & 0.4 \\ 0.2 & 0.4 & 1.2 \end{bmatrix}$$

Cholesky decomposition gives:

$$P = \begin{bmatrix} 1.0 & 0 & 0 \\ 0.3 & 0.84 & 0 \\ 0.2 & 0.40 & 1 \end{bmatrix}$$



# Cholesky example: Numerical illustration

Suppose we estimate the reduced form and obtain:

$$\hat{\Sigma}_u = \begin{bmatrix} 1.0 & 0.3 & 0.2 \\ 0.3 & 0.8 & 0.4 \\ 0.2 & 0.4 & 1.2 \end{bmatrix}$$

Cholesky decomposition gives:

$$P = \begin{bmatrix} 1.0 & 0 & 0 \\ 0.3 & 0.84 & 0 \\ 0.2 & 0.40 & 1 \end{bmatrix}$$

**Interpretation of first column:** A one-unit output shock causes:

- ▶ Output to increase by 1.0 contemporaneously
- ▶ Inflation to increase by 0.3 contemporaneously
- ▶ Interest rate to increase by 0.2 contemporaneously



# Sensitivity to variable ordering

Different orderings  $\Rightarrow$  Different economic assumptions

**Alternative 1:** Interest rate first (Taylor rule responds immediately)

$$i_t \rightarrow Y_t \rightarrow \pi_t$$

**Alternative 2:** Inflation first (price level responds to all shocks)

$$\pi_t \rightarrow Y_t \rightarrow i_t$$



# Cholesky identification: advantages & limitations

## Advantages:

- ▶ Simple to implement (built into most software)
- ▶ Always provides exact identification
- ▶ Useful benchmark for comparison
- ▶ Good starting point for empirical analysis

## Limitations:

- ▶ Relies on strong (often unrealistic) assumptions about timing
- ▶ Results can be sensitive to variable ordering
- ▶ May not reflect true economic structure

**Best practice:** Use Cholesky as a baseline, then explore alternative identification schemes.



Remember the identification problem.

$$B_0^{-1} \equiv \tilde{B} = \begin{bmatrix} \tilde{b}_{11} & \tilde{b}_{12} & \tilde{b}_{13} \\ \tilde{b}_{21} & \tilde{b}_{22} & \tilde{b}_{23} \\ \tilde{b}_{31} & \tilde{b}_{32} & \tilde{b}_{33} \end{bmatrix}, \quad \varepsilon_t \sim \mathcal{N}(0, I_3) \quad u_t = \tilde{B}\varepsilon_t$$

$$\Sigma_u \equiv \text{Cov}(u_t) = \tilde{B}\tilde{B}^\top = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{12} & \sigma_{22} & \sigma_{23} \\ \sigma_{13} & \sigma_{23} & \sigma_{33} \end{bmatrix}$$

with entries (six unique equations):

$$\sigma_{11} = \tilde{b}_{11}^2 + \tilde{b}_{12}^2 + \tilde{b}_{13}^2$$

$$\sigma_{12} = \tilde{b}_{11}\tilde{b}_{21} + \tilde{b}_{12}\tilde{b}_{22} + \tilde{b}_{13}\tilde{b}_{23}$$

$$\sigma_{22} = \tilde{b}_{21}^2 + \tilde{b}_{22}^2 + \tilde{b}_{23}^2$$

$$\sigma_{13} = \tilde{b}_{11}\tilde{b}_{31} + \tilde{b}_{12}\tilde{b}_{32} + \tilde{b}_{13}\tilde{b}_{33}$$

$$\sigma_{33} = \tilde{b}_{31}^2 + \tilde{b}_{32}^2 + \tilde{b}_{33}^2$$

$$\sigma_{23} = \tilde{b}_{21}\tilde{b}_{31} + \tilde{b}_{22}\tilde{b}_{32} + \tilde{b}_{23}\tilde{b}_{33}$$

Karel Mertens and Morten O. Ravn (2013).

“The Dynamic Effects of Personal and Corporate Income Tax Changes in the United States.” *American Economic Review*, 103(4): 1212–1247.

Mark Gertler and Peter Karadi (2015).

“Monetary Policy Surprises, Credit Costs, and Economic Activity.”  
*American Economic Journal: Macroeconomics*, 7(1): 44–76.

$$IRF_t^{(MP)} = \underbrace{A_1^{t-1}}_{\text{Estimated}} \begin{bmatrix} \tilde{b}_{11} & \tilde{b}_{12} & \tilde{b}_{13} \\ \tilde{b}_{21} & \tilde{b}_{22} & \tilde{b}_{23} \\ \tilde{b}_{31} & \tilde{b}_{32} & \tilde{b}_{33} \end{bmatrix} \underbrace{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}}_{\text{MP shock}} \quad \text{for VAR(1)}$$

We are only interested in responses to monetary policy shocks. So, to obtain IRFs, it is enough to identify the first column,  $[\tilde{b}_{11} \ \tilde{b}_{21} \ \tilde{b}_{31}]'$ .

The ordering of variables is inconsequential here; arranging the MPS first is just a convention.

# External instrument assumptions

- ▶ Relevance:  $\mathbb{E}[\varepsilon_{i,t}z_t] = \mathbf{Cov}(\varepsilon_{i,t}, z_t) \neq 0$ .
- ▶ Exogeneity (exclusion):  $\mathbf{Cov}(\varepsilon_{Y,t}, z_t) = 0$ ,  $\mathbf{Cov}(\varepsilon_{\pi,t}, z_t) = 0$ .
- ▶ Instrument is uncorrelated with lagged information used to form  $u_t$ .

Then:

$$\mathbb{E}[u_t z_t] = \mathbb{E} \left[ \underbrace{\tilde{B} \begin{bmatrix} \varepsilon_{i,t} \\ \varepsilon_{Y,t} \\ \varepsilon_{\pi,t} \end{bmatrix}}_{u_t} z_t \right] = \tilde{B} \begin{bmatrix} \mathbf{Cov}(\varepsilon_{i,t}, z_t) \\ 0 \\ 0 \end{bmatrix} = \mathbf{Cov}(\varepsilon_{i,t}, z_t) \begin{bmatrix} \tilde{b}_{i1} \\ \tilde{b}_{Y1} \\ \tilde{b}_{\pi 1} \end{bmatrix}$$

# Identification via covariance ratio

$$\mathbb{E} \left[ \begin{bmatrix} u_{i,t} \\ u_{Y,t} \\ u_{\pi,t} \end{bmatrix} z_t \right] = \text{Cov}(\varepsilon_{i,t}, z_t) \begin{bmatrix} \tilde{b}_{i1} \\ \tilde{b}_{Y1} \\ \tilde{b}_{\pi 1} \end{bmatrix}$$

Writing components,

$$\text{Cov}(u_{i,t}, z_t) = \text{Cov}(\varepsilon_{i,t}, z_t) \tilde{b}_{i1},$$

$$\text{Cov}(u_{Y,t}, z_t) = \text{Cov}(\varepsilon_{i,t}, z_t) \tilde{b}_{Y1},$$

$$\text{Cov}(u_{\pi,t}, z_t) = \text{Cov}(\varepsilon_{i,t}, z_t) \tilde{b}_{\pi 1}.$$

We normalize  $\tilde{b}_{i1} = 1$ , implying a one standard deviation shock to gauge the responses. Then, the first column is

$$\tilde{b}_1 = \frac{\text{Cov}(u_t, z_t)}{\text{Cov}(u_{i,t}, z_t)}$$

# Wild bootstrap: Testing robustness of IRFs

**Core question:** Is my IRF a robust economic relationship or just a historical accident?

## The method:

- ▶ Keep the **same shock magnitudes** and **same timing**
- ▶ Randomly flip the **signs** of historical residuals
- ▶ Create 1000+ alternative histories where shocks could have gone either way

## The test:

- ▶ **Narrow confidence bands**  $\Rightarrow$  Robust economic relationship
- ▶ **Wide confidence bands**  $\Rightarrow$  Result depends on historical accidents

**Intuition:** If your IRF survives when we randomly flip whether shocks were positive or negative, then it captures something fundamental about the economy, not just the particular sequence of ups and downs that happened in your sample.



# Wild bootstrapping method

Original VAR model:

$$Y_t = A_1 Y_{t-1} + A_2 Y_{t-2} + \dots + A_p Y_{t-p} + u_t$$

Step 1: Extract residuals

$$u_t = Y_t - \hat{A}_1 Y_{t-1} - \hat{A}_2 Y_{t-2} - \dots - \hat{A}_p Y_{t-p}$$

Step 2: Generate random signs

$$v_t = \begin{cases} +1 & \text{with probability 0.5} \\ -1 & \text{with probability 0.5} \end{cases}$$

Step 3: Create bootstrap residuals

$$u_t^* = v_t \cdot u_t$$

Key: Same shock magnitudes  $|u_t| = |u_t^*|$ , random signs  $v_t$



## Step 4: Generate bootstrap sample

$$Y_t^* = A_1 Y_{t-1} + A_2 Y_{t-2} + \cdots + A_p Y_{t-p} + u_t^*$$

## Step 5: Re-estimate

$$Y_t^* = \hat{A}_1 Y_{t-1}^* + \hat{A}_2 Y_{t-2}^* + \cdots + \hat{A}_p Y_{t-p}^* + u_t^*$$

Compute the impulse responses for this bootstrap sample. Repeat the procedure thousands of times and construct the 95% confidence interval from the resulting distribution.

- ▶ *Structural Vector Autoregressive Analysis*  
by Lutz Kilian and Helmut Lütkepohl
- ▶ Identifying Structural VARs with a Proxy Variable and a Test for a Weak Proxy by Kurt G. Lunsford